

WeiBot Robots in the Wild

A small social robot that invites you to sit next to it on a bench!

What is a robot?

Attributes:

- Execution of specific tasks with little/no human intervention
- It has a body and some kind of movement capabilities
- Has a certain degree of autonomy
- Attracts attribution of human categories on non-human entities (Anthropomorphism)

Yet, it is hard to explicitly define what a robot is since this depends on how it is perceived. After all they vacuum our carpets, serve in restaurants, work in the production or just play beer pong.

Observations of the "public"

Public Space

- Accessible to (almost) everyone
- Strongly regulated by social norms and emotions (for example *shame*)
- Potential interactions with strangers

Private Space

- Limited accessibility & social interactions
- No fear of judgement from others
- Personal (& public) rules
- People experience it as a familiar space



Study Design

Understanding of the term "public" helped us to choose an appropriate location to conduct the study. Robots in public places, in general, must deal with dynamic, multiparty scenarios, meaning high levels of two-sided interactions (human-robot interaction).

Perceived intimacy can be biased when interacting with a humanoid (human-like) robot, therefore we aimed for a *non-anthropomorphic* robot design.

Our research question is: How do people interact with a nonanthropomorphic robot in public and how do they perceive intimate practices, like hugging the robot?

We place the robot on a bench in the Weimarhallenpark and remote control the robot in order to interact with people walking by. During the interaction, we try to evoke an intimate feeling in people towards the robot by asking for *help, for a hug,* and *being carried* around.

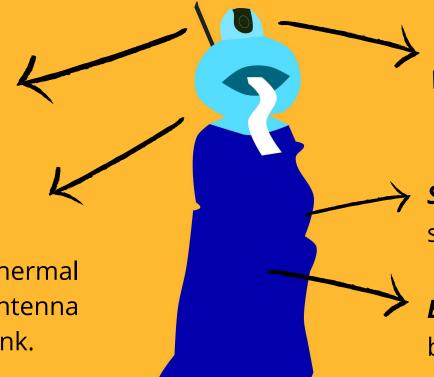
Lastly, our methods to study this, are *participatory* observations of interactions and participant interviews subsequently.

Prototype

Moving *antenna*, as an indicator to create attention during interaction.

The *head* is made out of plastic (easy to clean)

Other technical components in there: a thermal printer for communication, a sensor for the antenna movement, a microcontroller, and a power bank.



Webcam is a representation of an "eye", that holds the gaze of the interacting person.

Soft-feeling neoprene aims to create a nice soft surface to touch.

Body with a soft filling that is hard to balance and handle during the interaction.