

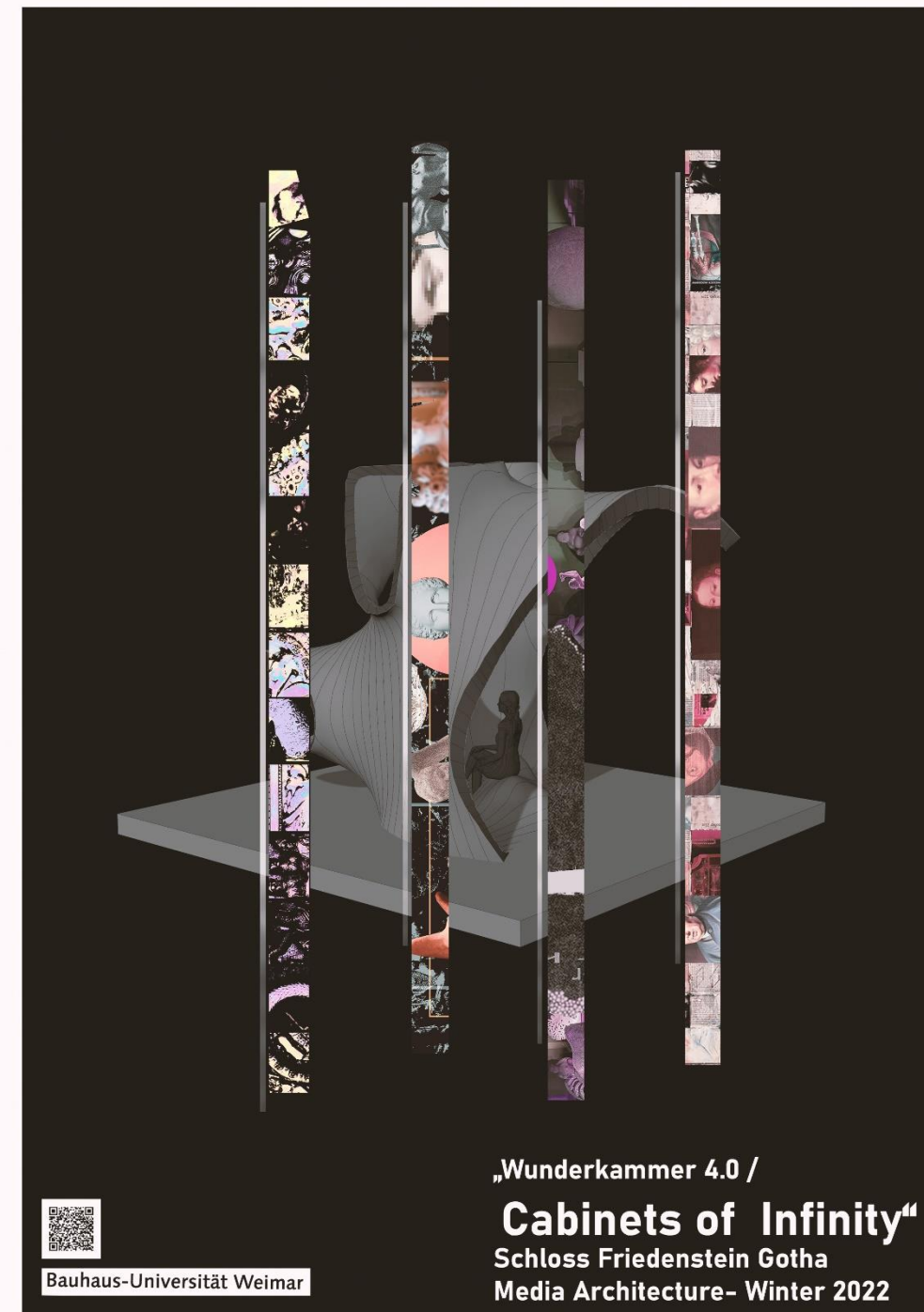
„Wunderkammer 4.0 / Cabinets of wonder“ Schloss Friedenstein Gotha

Betreuung: Prof. Bernd Rudolf, Prof. Andreas Kästner, Junior Prof. Reinhard König,

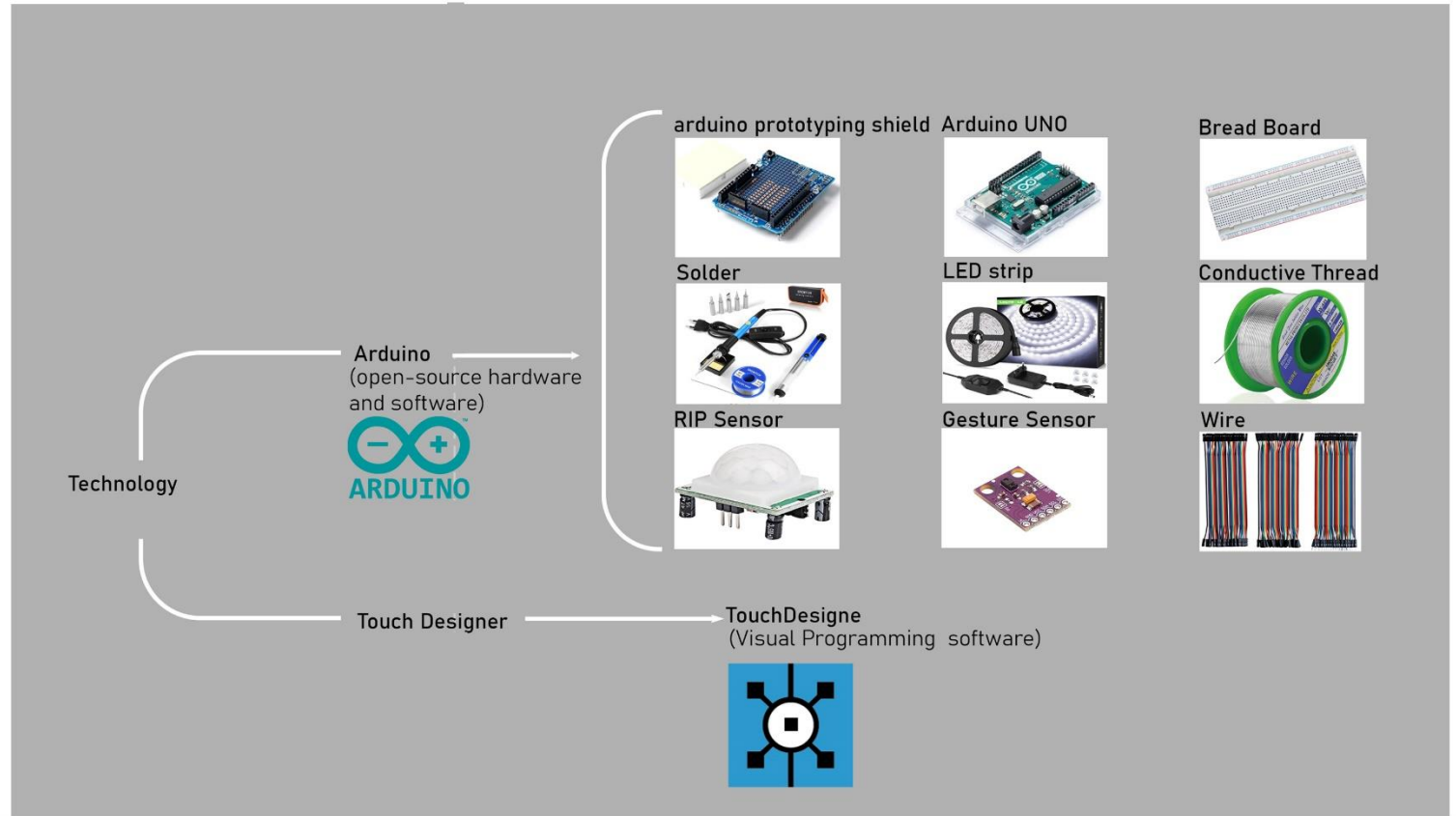
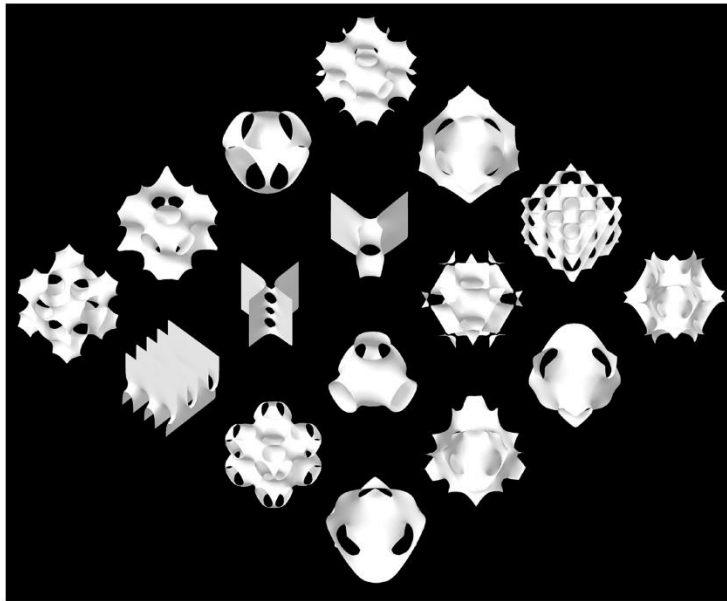
Dr. Sabine Zierold,

Nezar Abuhlaweh

Gastkritik: Stefan Kraus / Author: Zeinab Rahimi, Faezeh Mansourkhaki



Light ————— Shadow  
Movement  
Layers



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The fundamental design concepts of this two-layer pavilion is based on the baroque architecture concept of high decorative interior design and relatively simpler faced. The intention is to show pictures of art pieces through interactive LED screens and give the visitor the joy of moving the displayed photo collection by themselves. we have chosen four modules to show four categories of art pieces which are: Sculpture, Paintings, Patterns, and Objects.



Photo Category: Sculpture



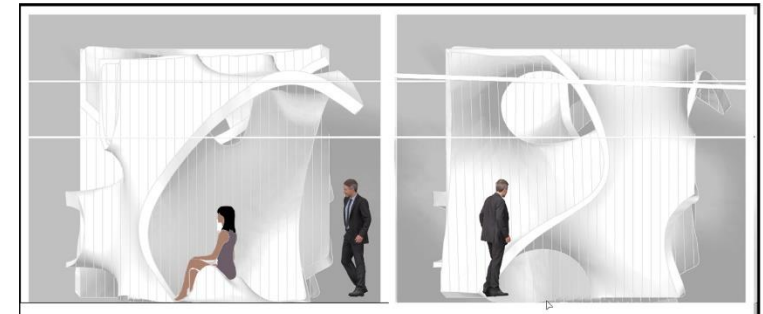
Photo Category: Pattern



Photo Category: Objects



Photo Category: Painting



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First collection- sculpture



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First collection- sculpture

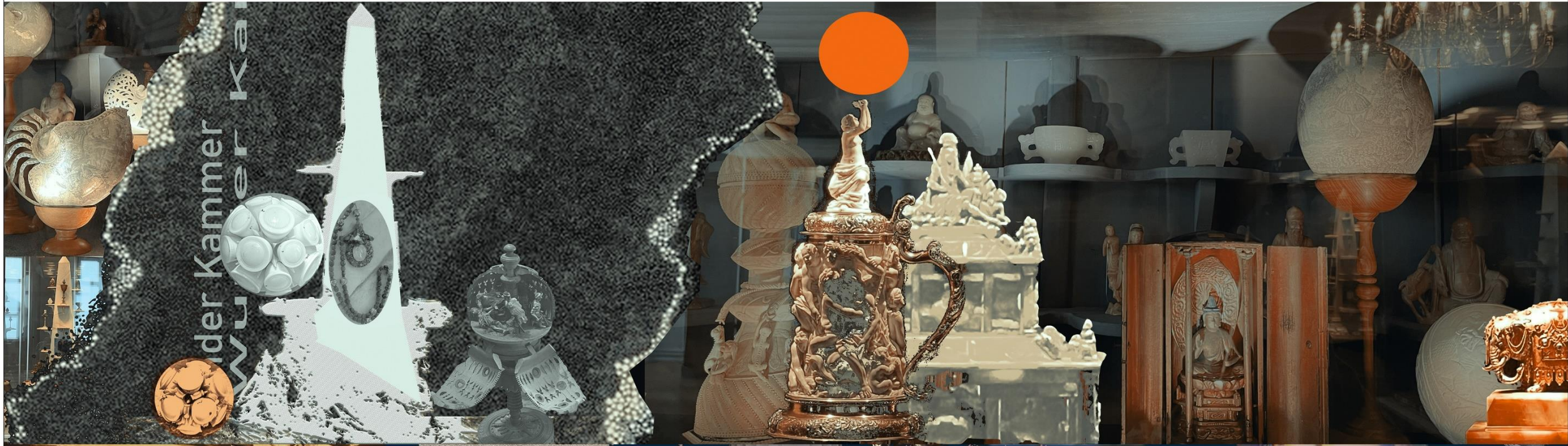


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First collection- sculpture



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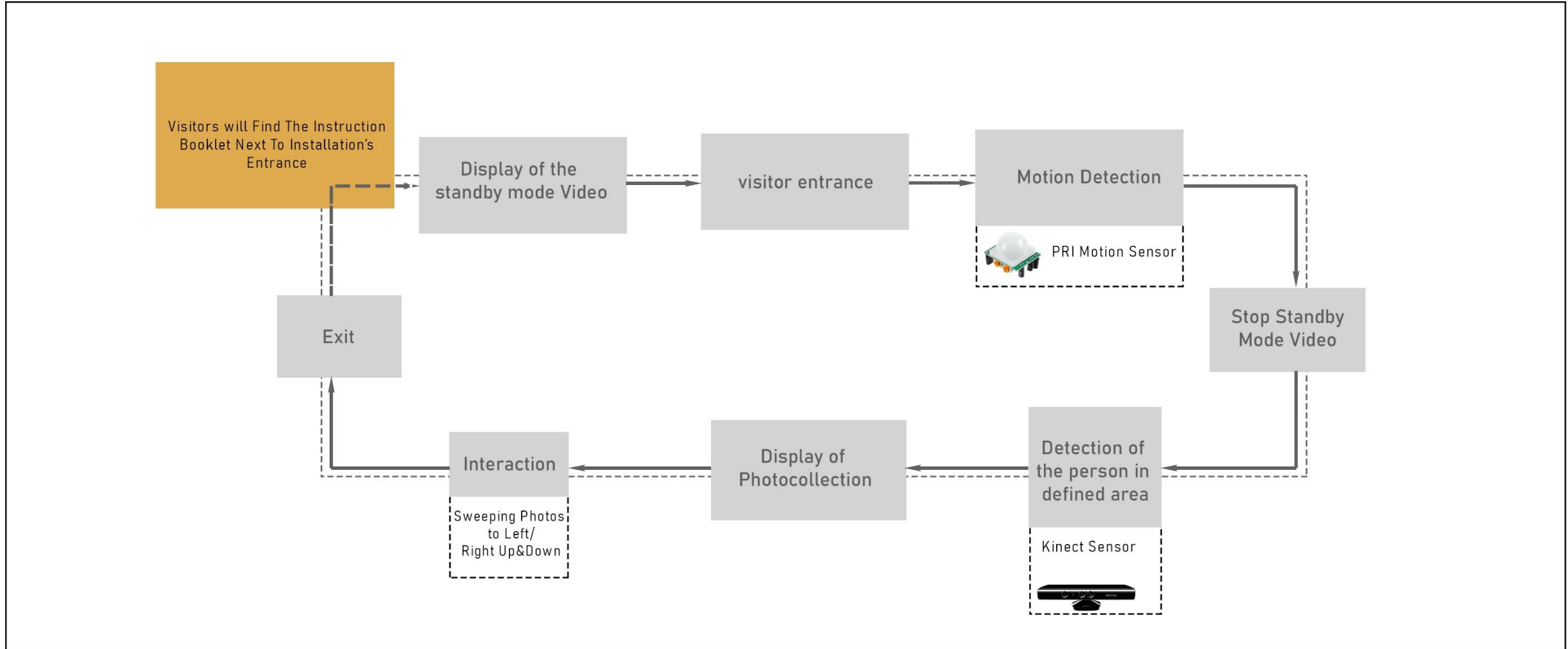
First collection- sculpture



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```
#include <Wire.h>
#include <SparkFun_APDS9960.h>

// Pins
#define APDS9960_INT 2 // Needs to be an interrupt pin

// Constants

// Global Variables
SparkFun_APDS9960 apds = SparkFun_APDS9960();
int isr_flag = 0;

void setup() {

  // Set interrupt pin as input
  pinMode(APDS9960_INT, INPUT);

  // Initialize Serial port
  Serial.begin(9600);
  Serial.println();
  Serial.println(F("-----"));
  Serial.println(F("SparkFun APDS-9960 - GestureTest"));
  Serial.println(F("-----"));

  // Initialize interrupt service routine
  attachInterrupt(0, interruptRoutine, FALLING);

  // Initialize APDS-9960 (configure I2C and initial values)
  if ( apds.init() ) {
    Serial.println(F("APDS-9960 initialization complete"));
  } else {
    Serial.println(F("Something went wrong during APDS-9960 init!"));
  }
}
```

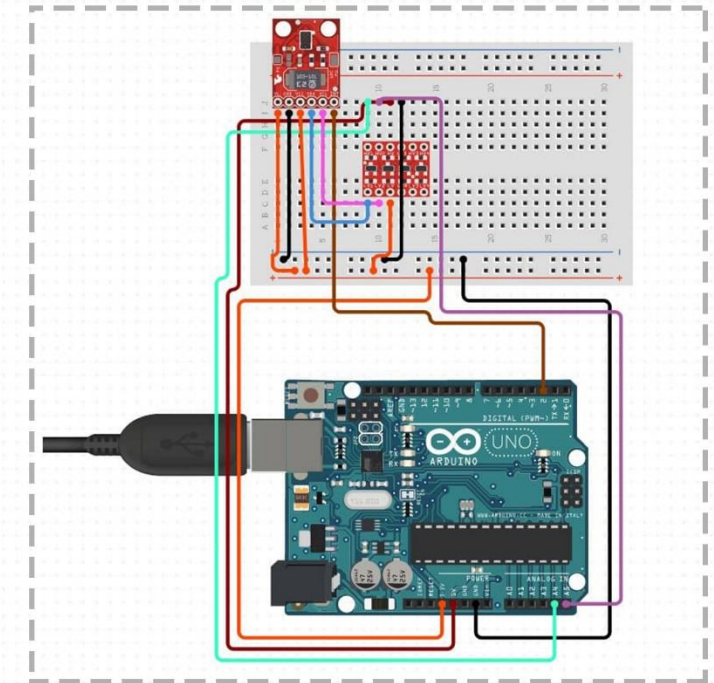
```
// Start running the APDS-9960 gesture sensor engine
if ( apds.enableGestureSensor(true) ) {
  Serial.println(F("Gesture sensor is now running"));
} else {
  Serial.println(F("Something went wrong during gesture sensor init!"));
}

}

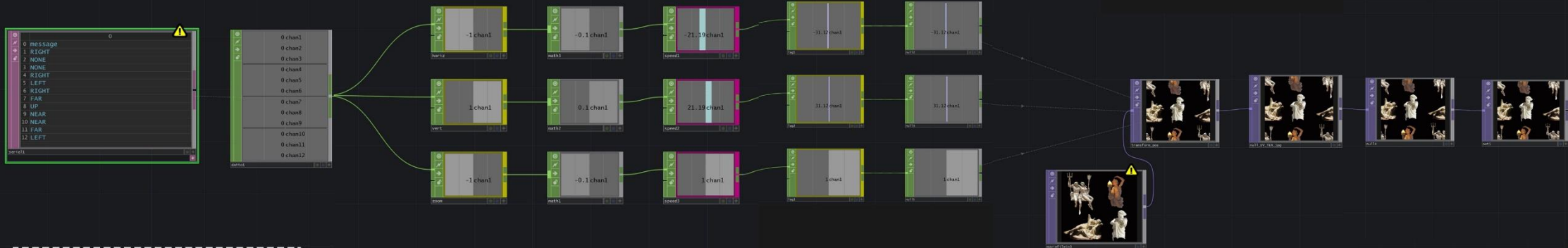
void loop() {
  if( isr_flag == 1 ) {
    detachInterrupt(0);
    handleGesture();
    isr_flag = 0;
    attachInterrupt(0, interruptRoutine, FALLING);
  }
}

void interruptRoutine() {
  isr_flag = 1;
}

void handleGesture() {
  if ( apds.isGestureAvailable() ) {
    switch ( apds.readGesture() ) {
      case DIR_UP:
        Serial.println("UP");
        break;
      case DIR_DOWN:
        Serial.println("DOWN");
        break;
      case DIR_LEFT:
        Serial.println("LEFT");
        break;
      case DIR_RIGHT:
        Serial.println("RIGHT");
        break;
      case DIR_NEAR:
        Serial.println("NEAR");
        break;
      case DIR_FAR:
        Serial.println("FAR");
        break;
      default:
        Serial.println("NONE");
    }
  }
}
```



Touch Designer inner shell code



```

1 # me - this DAT
2 #
3 # dat - the DAT that received the data
4 # rowIndex - the row number the data was placed into
5 # message - an ascii representation of the data
6 # Unprintable characters and unicode characters will
7 # not be preserved, use the 'bytes' parameter to get
8 # the raw bytes that were sent.
9 # bytes - byte array of the data received
10
11 def onReceive(dat, rowIndex, message, bytes):
12     #message = op('select1')[0,0]
13     #print(message)
14     if message == "RIGHT":
15         op('horiz').par.value0 = 1
16     elif message == "LEFT":
17         op('horiz').par.value0 = -1
18     elif message == "UP":
19         op('vert').par.value0 = 1
20     elif message == "DOWN":
21         op('vert').par.value0 = -1
22     elif message == "NEAR":
23         op('zoom').par.value0 = 1
24     elif message == "FAR":
25         op('zoom').par.value0 = -1
26     elif message == "NONE":
27         op('horiz').par.value0 = 0
28         op('vert').par.value0 = 0
29         op('zoom').par.value0 = 0
30     return
    
```

The code to connect the arduino to Touchdesinger and convert the input data ( from sensor) to move the photo on geometry



```

1 # me - this DAT
2 #
3 # channel - the channel object which has changed
4 # sampleIndex - the index of the changed sample
5 # val - the numeric value of the changed sample
6 # prev - the previous sample value
7 #
8 # Make sure the corresponding toggle is enabled in the CHOP Execute DAT.
9
10 def onOffToOn(channel, sampleIndex, val, prev):
11     op('speed1').par.resetpulse.pulse()
12     op('speed2').par.resetpulse.pulse()
13     op('speed3').par.resetpulse.pulse()
14     return
15
16 def whileOn(channel, sampleIndex, val, prev):
17     return
18
19 def onToOff(channel, sampleIndex, val, prev):
20     return
21
22 def whileOff(channel, sampleIndex, val, prev):
23     return
24
25 def onValueChange(channel, sampleIndex, val, prev):
26     return
    
```

The code used to reset the data



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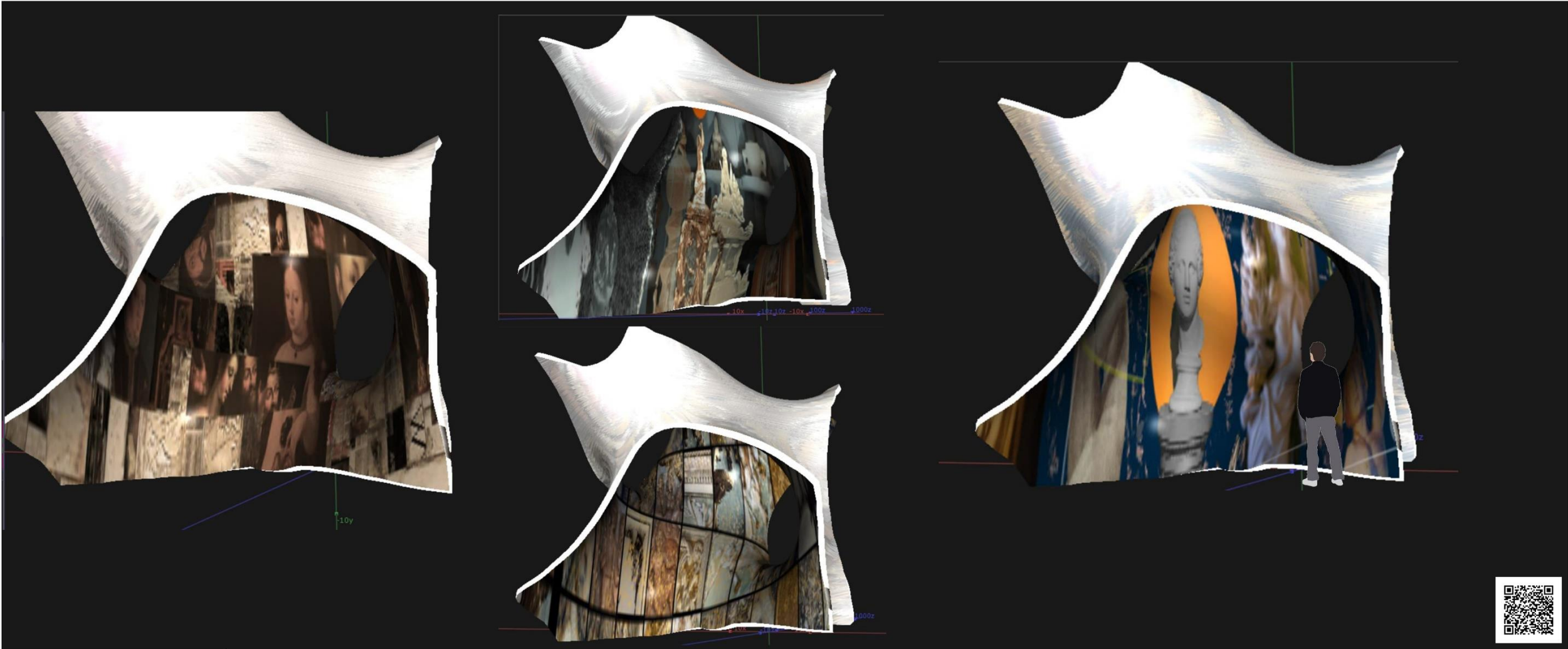
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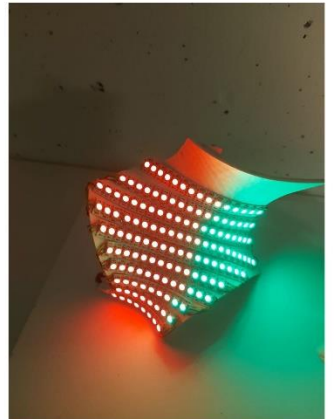
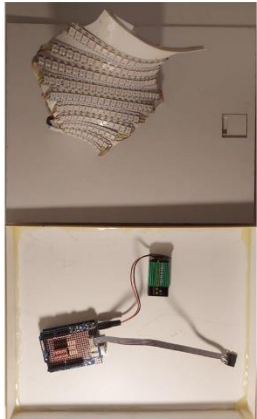
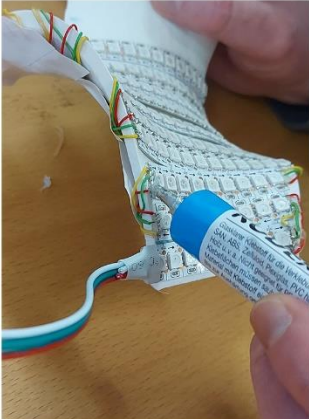
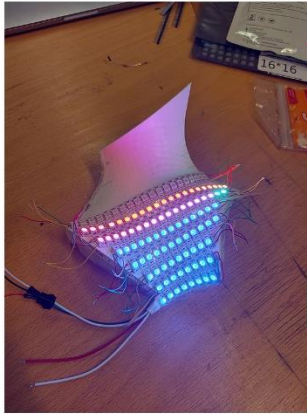
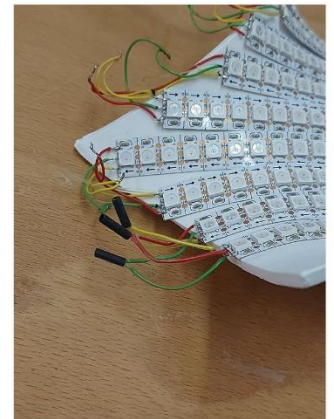
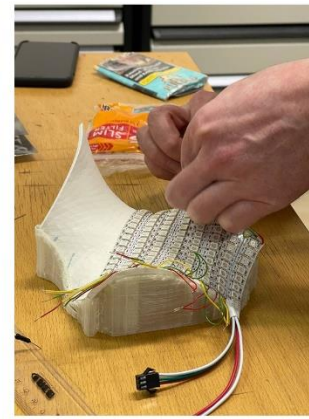
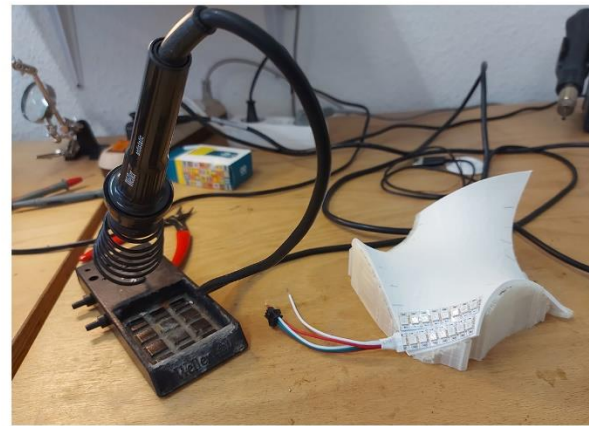
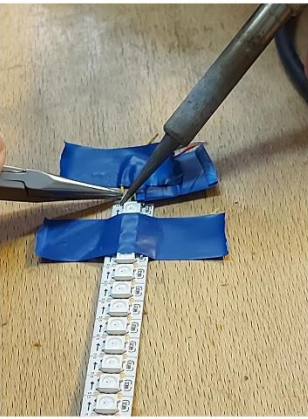
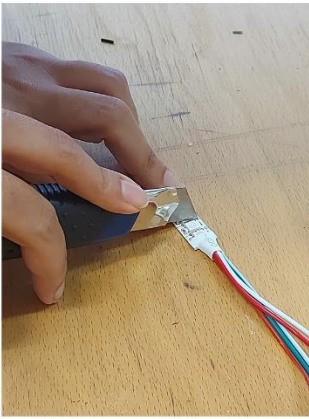
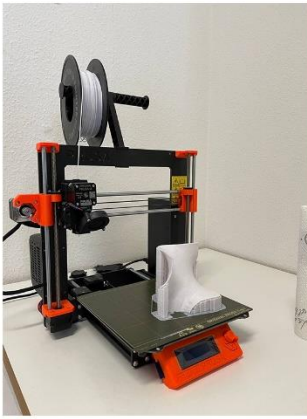


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physical prototype procedure



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THANK YOU!

