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#include "glutwindow.hpp"
#include "ppmwriter.hpp"
#include "pixel.hpp"

#include <iostream>
#include <cmath>

#include <boost/thread/thread.hpp>
#include <boost/bind.hpp>

#include "vector.hpp"
#include "matrix.hpp"

#ifdef __APPLE__
    #include <GLUT/glut.h>
#else
    #include <GL/glut.h>
#endif

// this is a dummy raytrace application
class application
{
public :

    // raytracing is initiated from here
    void start()
    {
        // the following code might also be executed in any method
        // just start your raytracing algorithm from here

        // size of a tile in checkerboard
        const std::size_t checkersize = 20;

        // get glutwindow instance
        glutwindow& window = glutwindow::instance();

        // create a ppmwriter
        ppmwriter image (window.width(), window.height(), "./
checkerboard.ppm");

        // for all pixels of window
        for (std::size_t y = 0; y < window.height(); ++y)
        {
            for (std::size_t x = 0; x < window.width(); ++x)
            {
                // create pixel at x,y
                pixel p(x, y);

                example_math3d();
            }
        }
    }
};

```

```

    // compute color for pixel
    if ( ((x/checkersize)%2) != ((y/checkersize)%2)) {
        p.rgb = color(0.0, 1.0, float(x)/window.height());
    } else {
        p.rgb = color(1.0, 0.0, float(y)/window.width());
    }

    // write pixel to output window
    window.write(p);

    // write pixel to image writer
    image.write(p);
}

// save final image
image.save();
}

// this method shows how to use the supplied classes for matrix, point
and vector
void example_math3d()
{
    // create some geometric objects
    math3d::point origin;
    math3d::point p0 ( 1.0, 5.0, -3.0 );
    math3d::vector v0 ( 2.0, 2.0, 1.0 );

    // some methods
    v0.normalize();

    // operator's
    math3d::vector v1 = origin - p0; // difference between points is a
vector
    double z_component = v0[2]; // random access into components of
point/vector

    // you can create transformation matrices
    math3d::matrix rotate = math3d::make_rotation_x ( M_PI / 4.0 ); //
rotation matrix: 45 deg about x axis
    math3d::matrix scale = math3d::make_scale ( 1.0, 2.0, 1.0 ); //
scale y axis
    math3d::matrix invrot = math3d::inverse(rotate);

    // concatenate transformations and transform points or vectors
    math3d::vector tv0 = rotate * scale * v0;
    math3d::point tp0 = rotate * scale * p0;
}

private : // attributes

```

```
// you may add your scene description here

};

int main(int argc, char* argv[])
{
    // set resolution and checkersize
    const std::size_t width = 400;
    const std::size_t height = 400;

    // create output window
    glutwindow::init(width, height, 100, 100, "CheckerBoard", argc, argv);

    // create a ray tracing application
    application app;

    // start computation in thread
    boost::thread thr(boost::bind(&application::start, &app));

    // start output on glutwindow
    glutwindow::instance().run();

    // wait on thread
    thr.join();

    return 0;
}
```