



1. MOTIVATION & INTRODUCTION



Fig. 1: Schematic view of the EWOD-driven micropump.

Micropumps have a wide range of applications, e.g., in medical technology, environmental analysis or lab-on-a-chip applications. In all these applications, robust and easy-to-integrate micropumps are desirable. The Electrowetting-On-Dielectrics-effect (EWOD effect) can be used to design a micropump without any moving components, which meets these requirements [1]. The project **objective** is the modelling, fabrication and characterization of this micropump.

2. FABRICATION



Fig. 2: Microcavities etched in a silicon substrate using DRIE.

manufacturing The process based İS on conventional fabrication methods of microsystems technology (MEMS). This enables a cost-effective and sustainable production. The structures are etched utilizing an optimized deep reactive ion etching (DRIE) process. The lid contains the **pump chamber** as well as the **Tesla** valves and the microcavities are placed inside of the base. The base and the lid are bonded utilizing a dry-film resist. The hydrophobization of the cavities is done using **Teflon**[™] to prevent the liquid from entering in the cavities. [2]



Fig. 3: Etched passive Tesla valve. The fluidic resistance differs strongly for the two flow directions.



Function principle:

A large number of **microcavities** are created within a silicon wafer. The surface of this cavities is hydrophobized to prevent the pumping liquid from entering the cavity. By applying an alternating voltage, the wetting properties can be varied, and thus, the liquid partially enters the cavities **periodically**. The resulting volume stroke can be rectified using **passive** microfluidic **Tesla valves**.

Fig. 4: (a) Fully assembled micropump; (b) Pump chamber and Tesla valves; (c) Base of the pump with microcavities

E-PunCh – Electrowetting Pump On a Chip

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3. SIMULATIONS



Fig. 4: Fluidic equivalent circuit model of the micropump.



The description of the micropump is done with the help of a **fluidic** equivalent circuit model. The efficient result is an and straightforward calculation [3]. In addition, this simulation method allows the pump design to be adapted to the target application.

particular challenge is the One design of efficient valve geometries. To find nearly optimal geometries of the Tesla valves, a self-developed topological optimization algorithm

Diodicity

4. CHARACTERIZATIONS

fluidic Characterization involves the the valve measurement of pump and performance. The Valve performance is determined the flow rate-dependent by diodicity (pressure difference ratio) and the pump performance is determined by a frequency- and voltage-dependent flow rate. Two measuring setups were developed for the **characterization**. [4]



Experimental setup for the Fig. **6**: measurement of the pump performance.



Fig. 5: Calculated material distribution together with the flow profiles during the optimization.

is used. This optimization algorithm 0.4

finds **near-optimal** valve geometries 0.2

by itself, leading to very efficient

valve designs.



Fig. 7: (left) Experimental setup for the measurement of the performance of a Tesla valve. (right) Comparison between the measured and simulated diodicities (higher is better). Black curve shows performance of a state-of-the-art valve.

References:

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[3] Bohm, S., Dittrich, L., Runge, E., Three-dimensional time resolved fluid mechanics simulation of an EWOD-driven micropump, COMSOL Conference Europe (2020) [4] Bohm, S., Dittrich, L., Runge, E., Modellierung, Fertigung und Erprobung einer neuartigen EWOD betriebenen Mikropumpe, MST-Kongress, Berlin (2019)

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