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# Occlusion Culling for Sub-Surface Models in Geo-Scientific Applications

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Virtual Environments Research

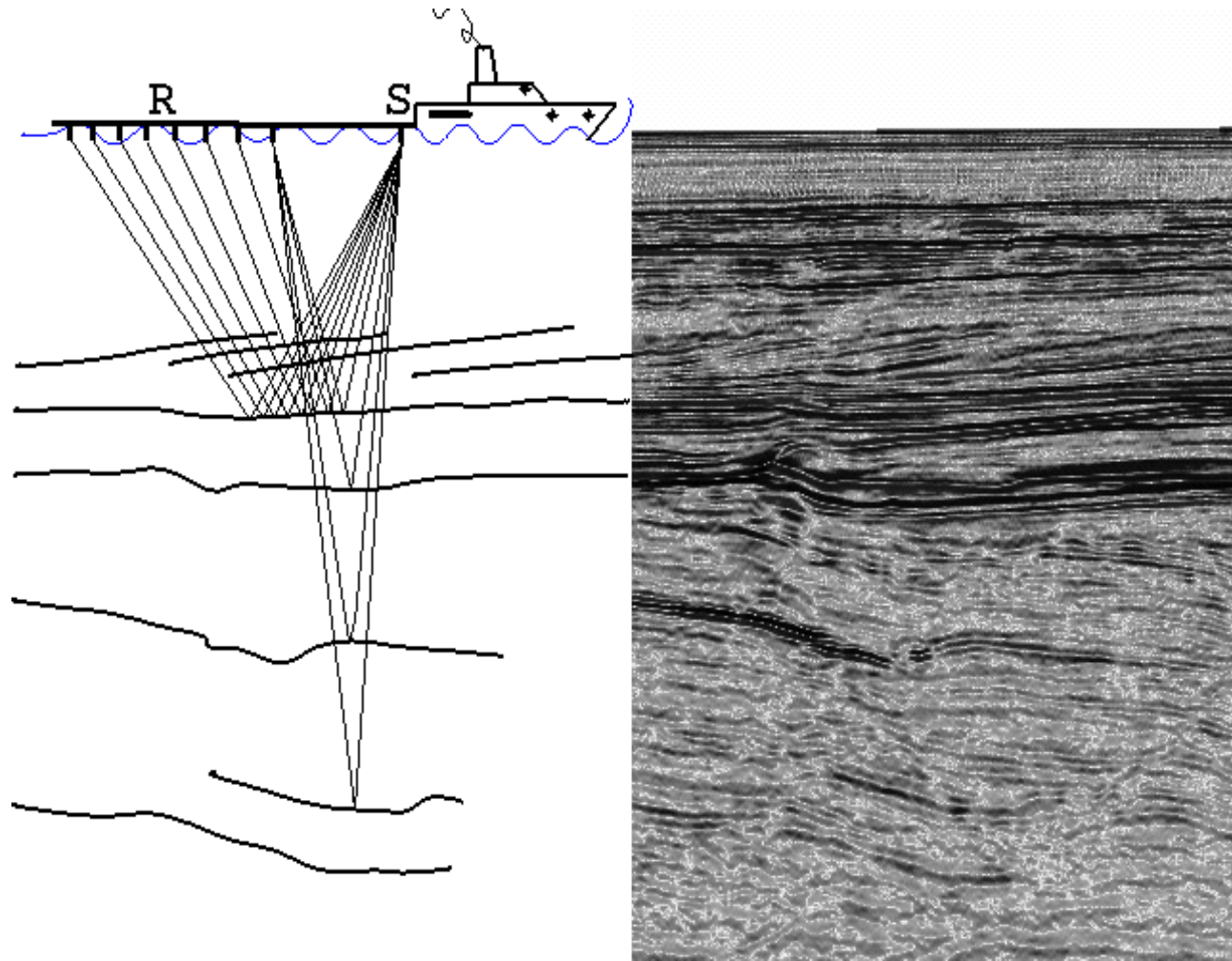
Fraunhofer IMK

Sankt Augustin, Germany

Bauhaus-University Weimar

Weimar, Germany

# Reflection Seismic



## Occlusion Culling

# Used Data Types

## ❑ Horizons

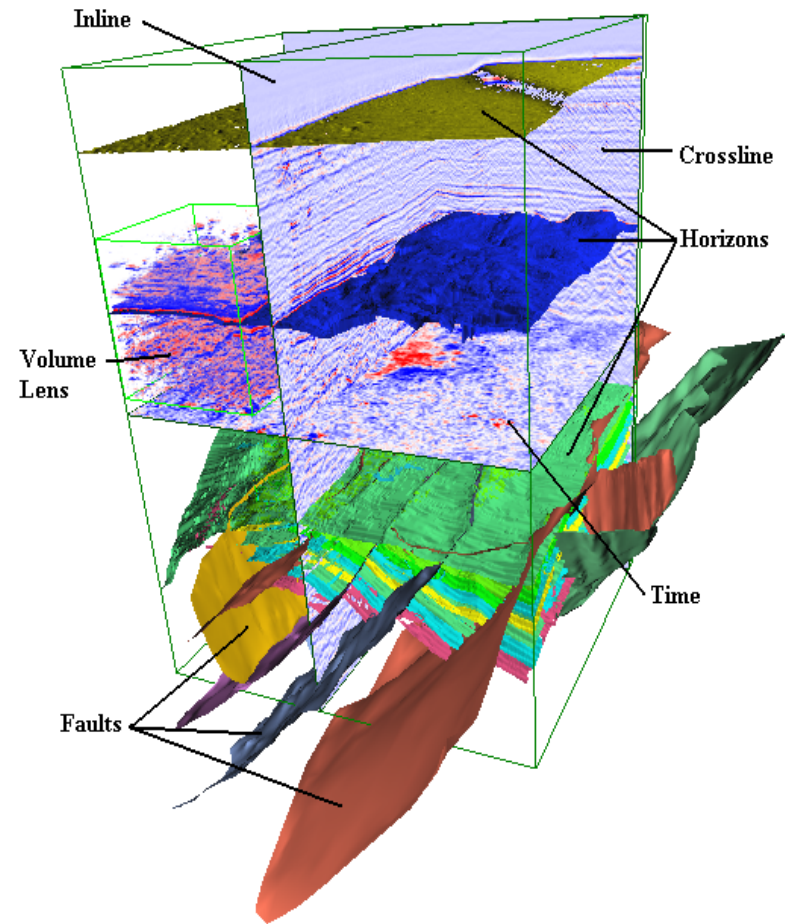
- High resolution
- Layered
- Often height fields

## ❑ Faults

- Often lower resolution than horizons

## ❑ Volumes

- Slices
  - Opaque
  - Few polygons
- Volume rendering
  - Semi transparent
  - Does not significantly occlude – may be occluded



## Occlusion Culling

# Occlusion Culling

## Basic idea

- Don't render invisible parts of the scene
- But how to know which parts are invisible?

## Naive approach

- Sort scene front to back
- For each object in front to back order
  - Submit occlusion query using the bounding box
  - If object's bounding box is visible
    - Render object

## Helps for scenes with high depth complexity

## Requires sorting

## Bounding box is not very precise

## Requires waiting for results of occlusion queries – stalls graphics pipe

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## Occlusion Culling

# Occlusion Queries in Hardware

- nVidia and ATI support occlusion queries in hardware**
  - Setup occlusion query
  - Render object
  - Result: the number of the visible pixels of the object
  
- Problem: if you ask for the result right after you render, the graphics pipeline needs to finish computing the partial image before the result can be returned**
  
- Better: render a collection of objects and ask for the occlusion results afterwards**

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## Occlusion Culling

# Basic Algorithm

## ❑ Preprocess

- Generate low resolution objects
- Divide objects into tiles

## ❑ First pass – create depth image

- Disable lighting, shading, texturing and frame buffer writes
- Clear depth buffer
- Render low resolution objects and additional occluders

## ❑ Second pass – query visibility

- Disable depth buffer writes
- Render low resolution objects with occlusion queries
- Read results of occlusion queries. Object is “visible”, if the number of visible pixels is above of a defined threshold

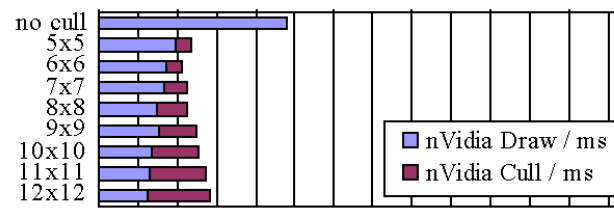
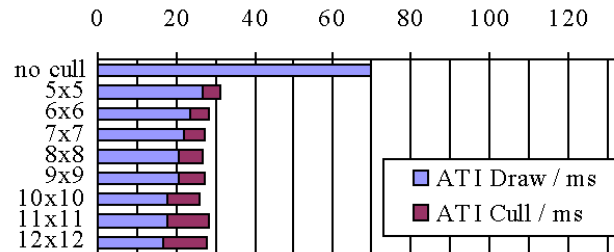
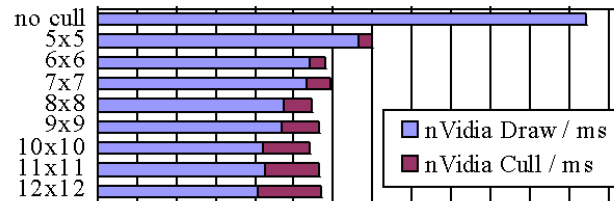
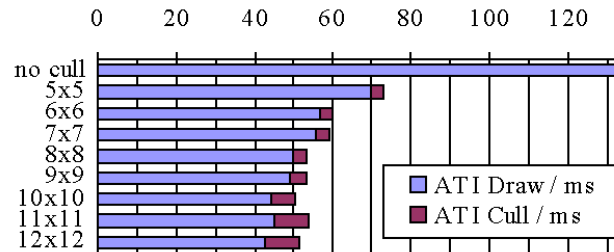
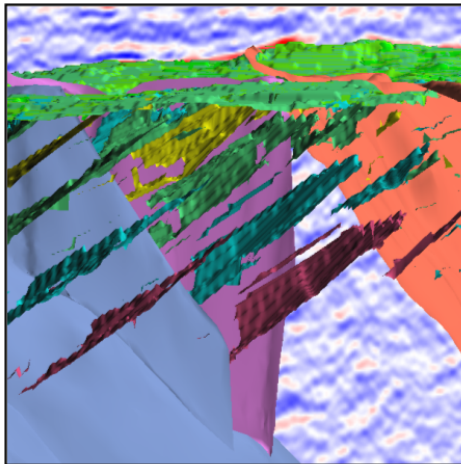
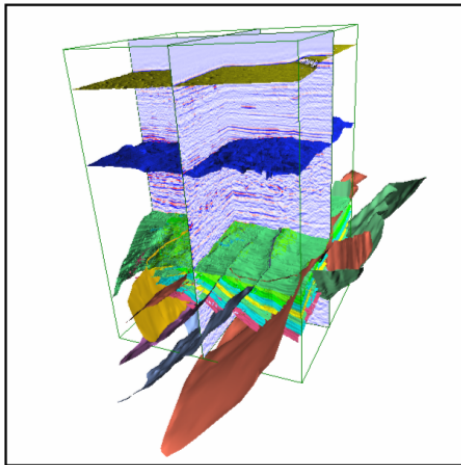
## ❑ Third pass – render visible objects

- Enable lighting, shading and texturing
- Enable depth and frame buffer writes and clear both buffers
- Render all “visible” high resolution objects

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## Occlusion Culling

# Benchmarks



## Occlusion Culling

# Conclusions and Future Work

**Simple and easy to implement**

**Efficient**

- No sorting
- More precise than bounding boxes
- Stalls graphics pipe only once per frame

**Works for dynamic scenes**

**Small overhead**

- Rendering of low resolution objects (1:100 reduction works)
- No lighting, texturing or pixel shaders
- Worst case: requires three times the fill rate
- Reduce fill requirements: use smaller image for pre-rendering

**Should be combined with level-of-detail rendering**

**Develop occlusion relationship preserving mesh simplification algorithms and measures that predict potential occlusion errors**

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## Occlusion Culling