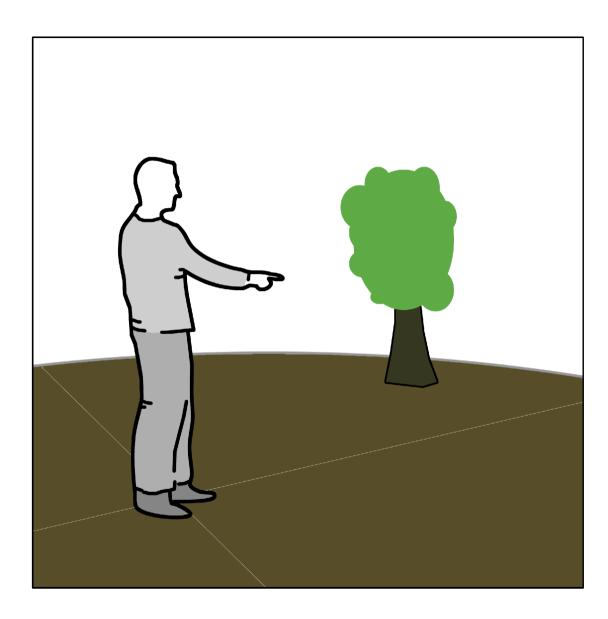


Alexander Kulik, Roland Blach, Bernd Fröhlich



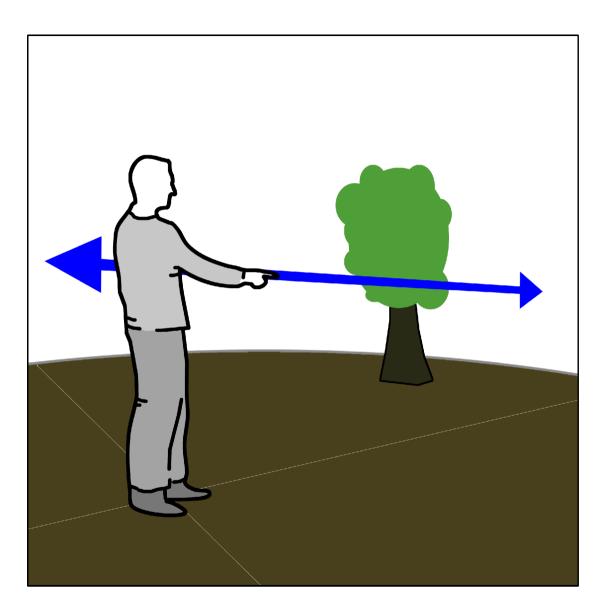






Horizontal spatial structure (due to gravity)

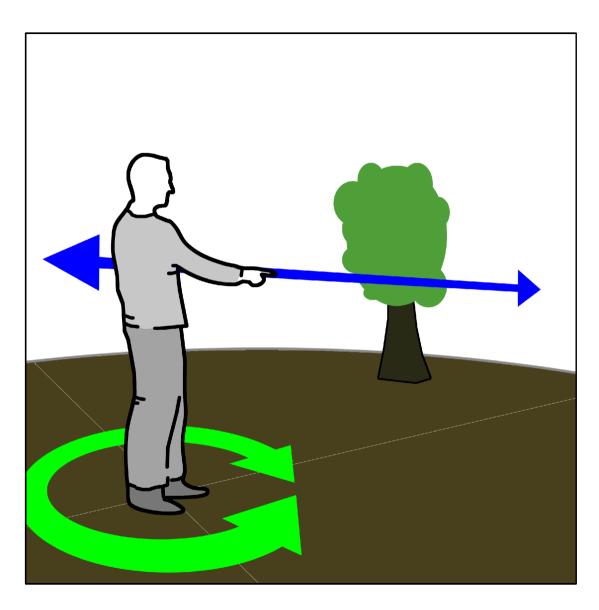




Terrain following navigation is a 2DOF Task.

- Translation along the pointing direction

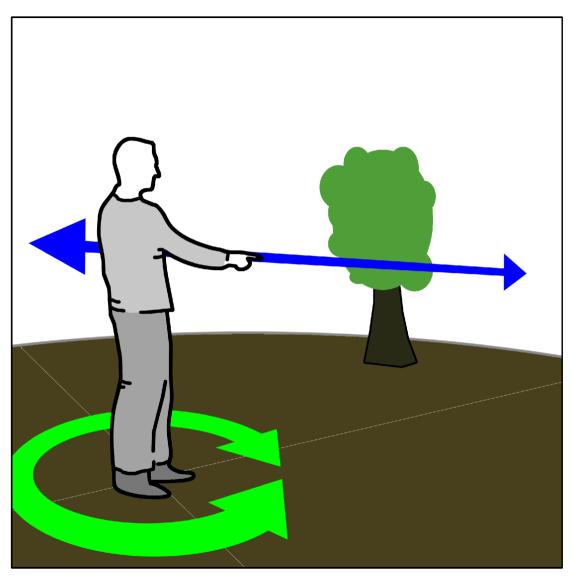




Terrain following navigation is a 2DOF Task.

- Translation along the pointing direction
- Pointing direction (Heading)

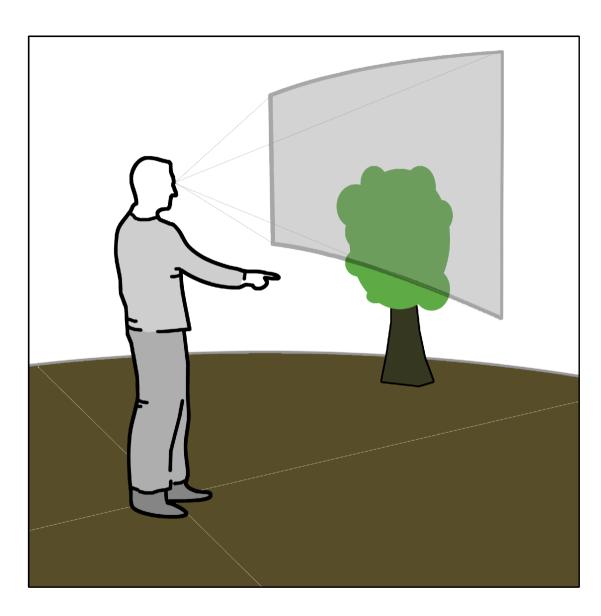




Terrain following navigation is a 2DOF Task.

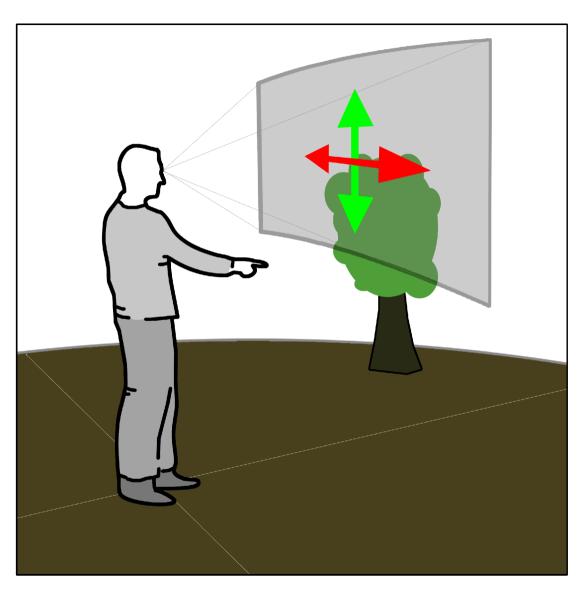
- Translation along the pointing direction
- Pointing direction (Heading)
- + Pitch for free movement
- Simultaneously required DOF





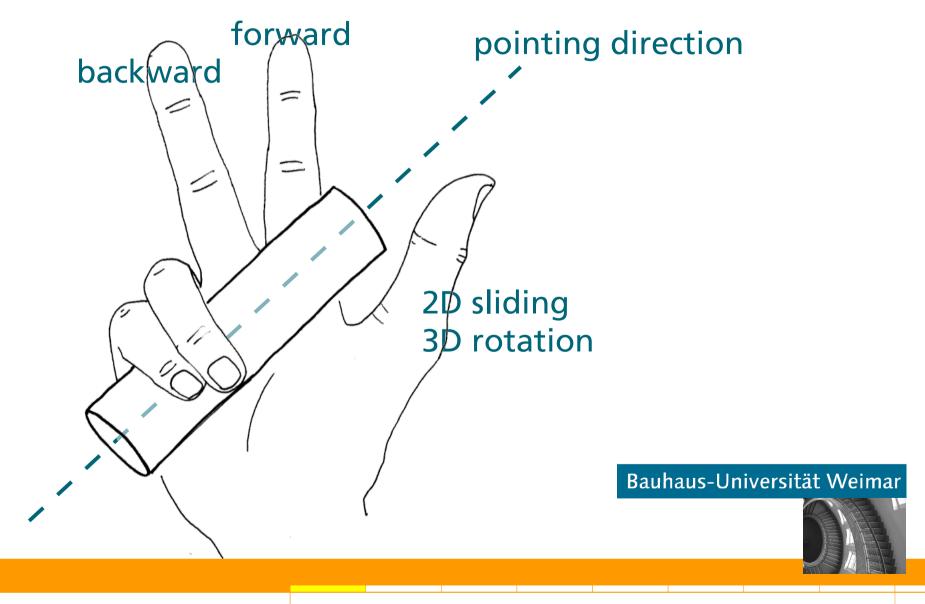
Translation parallel to the 2D image plane (sliding)





Translation parallel to the 2D image plane (sliding)

- Vertical axis
- Lateral axis
- Simultaneously required DOF

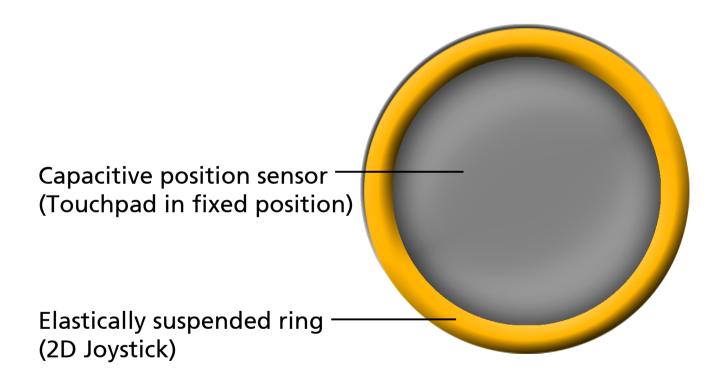


Sensor Configuration:

- Gyroscopic rotation tracker
 - pointing direction
- 2. Rocker lever
 - forward / backward
- 3. Groovepad
 - 2D sliding
 - 3D rotation



The Groovepad:

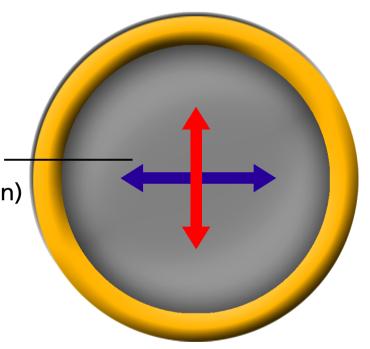




Thumb gestures on the Groovepad:

Rotation

Capacitive position sensor — (Touchpad in fixed position)



Isotonic rotation controller:

- Pitch

- Roll

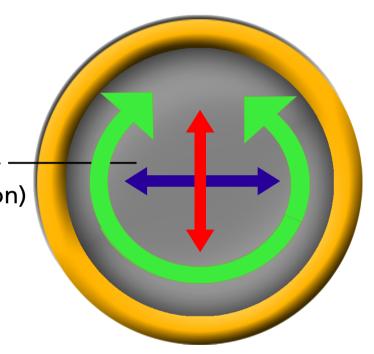




Thumb gestures on the Groovepad:

Rotation

Capacitive position sensor — (Touchpad in fixed position)



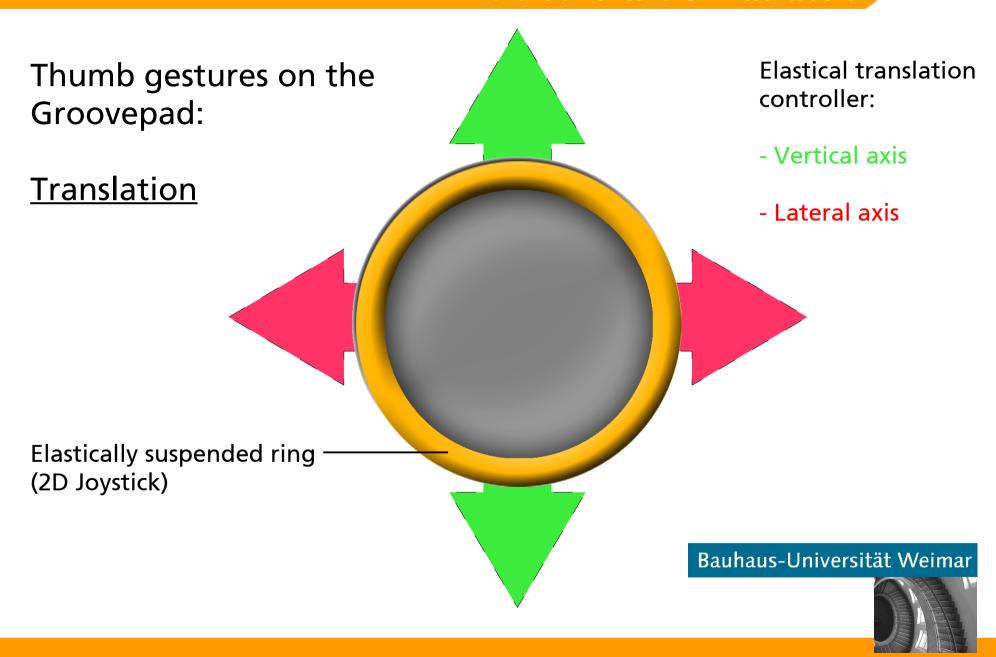
Isotonic rotation controller:

- Pitch
- Roll
- Head

Note: the surrounding ring guides the thumb

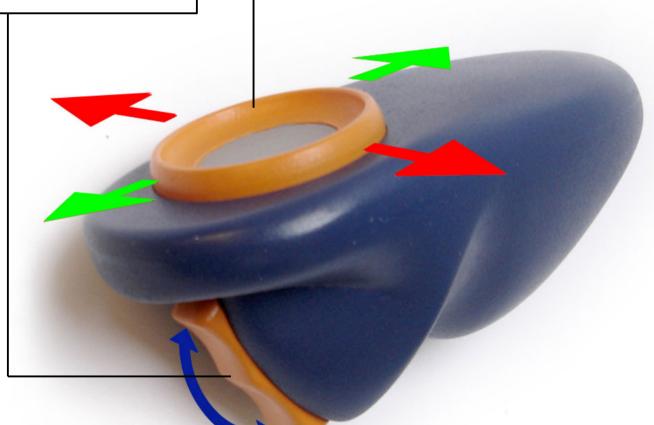
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A Handheld Device for 3D-Presentations



Elastical devices

- velocity controlled translation



- Vertical axis

- Lateral axis

- Longitudinal axis

Isotonic devices

- position controlled rotation

- Pitch
- Roll
- Head



Context / Requirements

Interaction / Device

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Conclusions

- Sensor arrangement matches with interaction techniques
- Initial user studies confirm the usability for the designated applications.

Future work

- Refinements of the hardware design
- Long term user studies

Thank you for your attention!

