

## 2 - Algorithm Complexity

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## Complexity

### Definition

## Hands-on Examples: Sorting

- Selection Sort
- Insertion Sort
- Bubble Sort
- Shell Sort
- Quicksort
- Heap Sort

# Algorithm Complexity

- Maybe we have more than one algorithm solving one problem.
- We need a way to compare speed among them.
  - Can use execution timing?
  - No, because it depends on machine
  - Maybe then counting operations?
  - Their number depends on data
  - Besides, which operations should one count?  
Small remark on mathematicians...
  - Speed depends on data size
  - Thus its speed needs to filter it out

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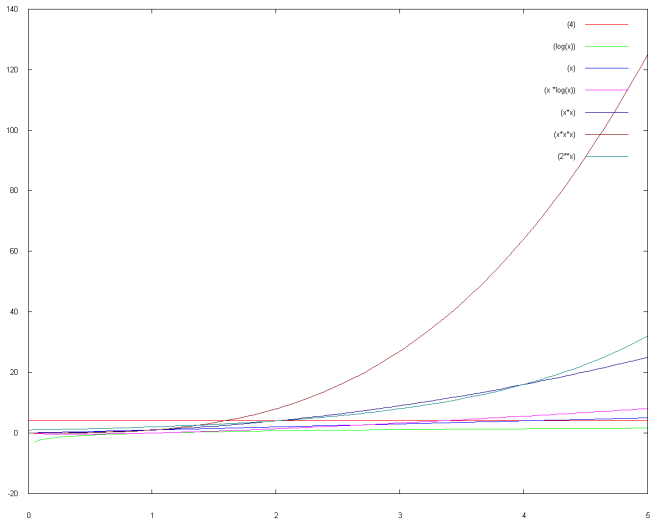
# Algorithm Complexity

- Suppose  $N$  is the size of the data to be processed.
  - Constant time: The instructions of the algorithm are a finite number and independent from amount of data.
  - Logarithmic time: The instructions of the algorithm are repeated an  $\mathcal{O}(\log N)$  number of times or a finite number of times.
  - Linear time: The instructions of the algorithm are repeated an  $\mathcal{O}(N)$  number of times or less.
  - $N \log N$  time: The instructions of the algorithm are repeated an  $\mathcal{O}(N \log N)$  number of times or less.
  - Quadratic time: The instructions of the algorithm are repeated an  $\mathcal{O}(N^2)$  number of times or less.
  - Cubic time: The instructions of the algorithm are repeated an  $\mathcal{O}(N^3)$  number of times or less.
  - Exponential time: The instructions of the algorithm are repeated an  $\mathcal{O}(a^N)$  number of times or less.



# Complexity

- The resulting functions look as follows:



## Complexity: definition and computations

- If the program execution time  $X \geq 0$  is such that for a given positive function  $f(N)$ ,  $\lim_{N \rightarrow \infty} \frac{X}{f(N)} \leq K$  for some  $K > 0$ , then execution time is  $\mathcal{O}(f(N))$ .
- When an algorithm can be decomposed in more parts, the arithmetic of complexity is like computations at infinity.
  - If the algorithm has 3 consecutive steps, running in  $\mathcal{O}(f_1(N))$ ,  $\mathcal{O}(f_2(N))$ , and  $\mathcal{O}(f_3(N))$ ,  
 $\implies$  its complexity is  $\mathcal{O}(|f_1(N)| + |f_2(N)| + |f_3(N)|) = \text{Max}_i |f_i(N)|$ , for  $N > N_0$ .
  - If the algorithm has 2 nested steps, running in  $\mathcal{O}(f_1(N))$  and  $\mathcal{O}(f_2(N))$ ,  
 $\implies$  its complexity is  $\mathcal{O}(|f_1(N)| \cdot |f_2(N)|)$ .
  - For a proof, just unroll the limit definition.

## Complexity: hands on with sorting

- This sounds very abstract: let us make a good example: sorting
- What is sorting? order a given set according to an order relation.
- What is an order relation?
- It is a relation in a set  $S$  among pairs of elements such that it satisfies the following properties:
  1. reflexive:  $\forall a \in S, a \leq a$ ,
  2. antisymmetric:  $a \leq b$  and  $b \leq a \iff a \equiv b$ ,
  3. transitive:  $a \leq b$  and  $b \leq c \implies a \leq c$ .
- Example: telephone directory uses lexicographical order

# Sorting

- The sorting problem:

Given an array of  $N$  data

$\implies$  Order the array elements according to given order relation

- Basic method used: compare and swap two elements
- Efficiency: depends on speed and memory usage
  - Speed: can be estimated through the number of compares and swaps
  - Memory usage: Here not relevant due to work "on the array".
- A method is said to be stable if the relative position of elements with the same key is not changed.

$1_a, 2_a, 1_b, 2_b, 2_c, 2_d, 3 \implies 1_a, 1_b, 2_a, 2_b, 2_c, 2_d, 3$

# Selection sort

- Sort through direct selection
- Idea:
  - Look for smallest element
  - Swap with first element
  - Move to second element
  - Repeat with rest of array
- Speed: How many swaps and compares do I do?
- 1st run: Max  $(N - 1)$  compares and 1 swap.
- 2nd run: Max  $(N - 2)$  compares and 1 swap ...
- ... till the vector is finished.
- Now, the sum of the first  $(N - 1)$  integers equals  $n * (n - 1) / 2$ , thus the whole becomes
- Total:  $\frac{(N)(N-1)}{2} \propto N^2 \implies \mathcal{O}(N^2)$ .

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# Insertion sort

- Sort through insertion
- Idea:
  - Choose a still unsorted element (first time: first element)
  - Put it in the right place among already sorted elements
  - Take next unsorted element until whole array is sorted
- Speed:
  - Average case: Depends on order of elements.
  - Worst case: Take all  $N$  elements, and insert them as last (i.e. compare with  $0, 1, 2, \dots, N - 1$   
 $\frac{N(N-1)}{2}$  compares.
- Total:  $\mathcal{O}(N^2)$ .
- BUT: When data almost sorted:  $\mathcal{O}(N)$ .



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# Bubble sort

- Sort through swapping
- Idea:
  - Move through array from left to right
  - Swap elements if they are in wrong order
  - Repeat until there is nothing left to swap.
- Speed:
  - At each step  $i$ :  $N - i$  compares, and  $\leq N - i$  swaps.
  - At most  $N$  steps (last moved to first).
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# Shell sort

- Improved insertion sort (Donald Shell)
- Idea:
  - We subdivide into subsets (like a matrix) by picking the  $s_n$ -th element  $s_0 = 1, s_{i+1} = 3s_i + 1$   
 $\implies \{1, 4, 13, 40, 121, 364, \dots\} = S$
  - Order elements in each subset with insertion sort
  - Resubdivide into new subsets by picking  $s_{n-1}$ -th element.
  - Order elements in each new subset with insertion sort
  - The  $S_n$  sequence works always as long as last sort step is one
- Speed:
  - The speed is dependent on the sequence  $s_i$  used<sup>1</sup>..
  - Worst case:  $\mathcal{O}(N^{3/2})$  for sequence  $\{1, 4, 13, 40, 121, 364, \dots\}$ .
  - Best case:  $\geq N^{1+c/\sqrt{M}}$  compares for N elements in M passes.
  - Average case for S: possibly  $\mathcal{O}(N^{5/4})$  or  $\mathcal{O}(N \log N^2)$

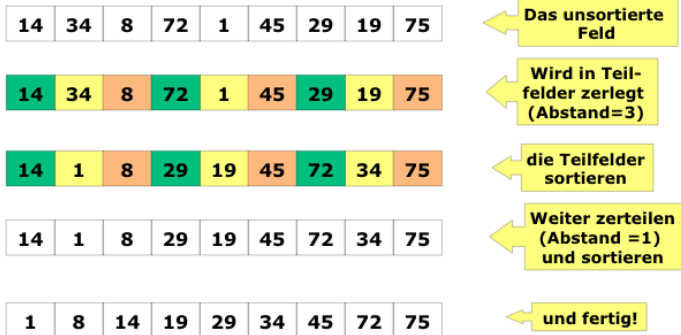
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# Shell sort



- This also shows how speedy the algorithm is.



# Comparison

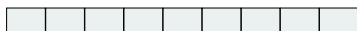
	SelectionSort	InsertionSort	ShellSort
Comparisons Ave.; Worst	$N^2/2$ ; $N^2/2$	$N^2/2$ ; $N^2/2$	$N^{5/4}$ ; $N^{3/2}$
Comparisons Ave.; Worst	$N$ ; $N$	$N^2/8$ ; $N^2/4$	$N^{5/4}$
When to apply	When data $\gg$ than key	When data almost sorted	General case

# Quicksort

- General purpose sorting.
- Developed by Hoare in 1960.
- Divide and conquer algorithm.
- Idea:
  - Choose one element  $w$  arbitrarily, the pivot.
  - Subdivide array in two parts:
    - Set  $A_1$  of elements  $\leq w$
    - Set  $A_2$  of elements  $> w$
  - If  $A_1$  and  $A_2$  are sorted, END.
  - Else sort  $A_1$  and  $A_2$  recursively.



Elements  $\leq w$



Elements  $> w$

# Quick Sort

- Suppose our array to sort is  $[a_1, \dots, a_N]$
- How do we do the partitioning?
- With indexes!
- Choose element  $a_r = w$  as pivot
  - Swap  $a_r = w$  and  $a_N$  (move pivot to end)
  - Take 2 indexes  $l = 1, h = N$
  - Increase  $l$  until you find an element  $a_l > w$ .
  - Decrease  $h$  until you find an element  $a_h \leq w$ .
  - Swap  $a_l$  and  $a_h$ .
  - Repeat until  $l \geq h$ .
  - Now swap  $a_l$  and  $w$ : this brings  $w$  at the right place in the field.
- Now do same for arrays  $a_1, \dots, a_l = w$  and  $a_{l+1}, \dots, a_N$

## Quick Sort: an example

a m h e r e t o b e s o r t e d ← Original String

amheretobesorted	Choose pivot (half of field)
amheretdbesorted	Swap pivot with last place
<u>a</u> mheretdbesorted	Set running indices
am <u>h</u> eretdbesorted	count up $l$ till $a_l > w$
amhe <u>r</u> etdbesorted	count down $h$ till $a_h \leq w$
amhe <u>e</u> etdbesortr	swap
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amheeee <u>o</u> dbestrtr	count down $h$ : indexes meet
amheeee <u>o</u> db <u>e</u> otrtrs	Swap $a_l$ and $w$
	Check if trivial case
amheeee <u>o</u> db <u>e</u> o trtrs	Separate vectors and continue until sorted

# Quicksort speed

Speed:

- Average case needs  $2N \log N$  comparisons  
 $\implies \mathcal{O}(N \log N)$
- Worst case: I always choose the pivot so that it is extreme: in this case I need  $N$  and not  $\log N$  steps  
 $\implies \mathcal{O}(N^2)$

# Heap Sort

- A heap is a binary tree, such that each father node is greater or equal to its children nodes.
- This implies the root of the heap is the biggest node.

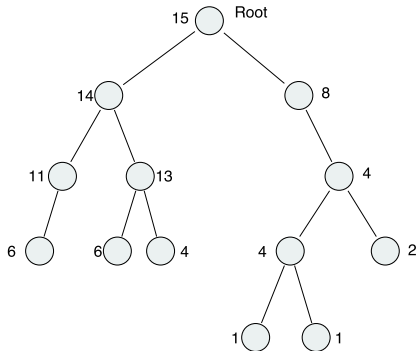


Figure: A heap.

# Heap Sort

- How do I build a heap?
- Simple: initialize a tree with one element
- Insert node at free leaf.
- Compare with father, and swap if its smaller
- Push it upwards, until heap condition is satisfied
- Do this for all new elements to sort

# Heap Sort

- How do I sort from a heap?
- Simple: pick root
- Take last leaf, move to root
- Push down new root to where it belongs (restore heap condition).
- Pick again from root until tree is empty



# Heap Sort

- Speed:
- Algorithm in two parts:
  - Construction of tree: maximum  $N \log N$  comparisons
  - Extraction: again  $N \log N$  comparisons
- Thus:  $2N \log N$  comparisons!!  $\implies \mathcal{O}(N \log N)$
- Real advantage: by dynamic sorting (constant inserts) resorting real fast due to insertion of single elements and extraction.